

# NCS-TT106H-V2.0 Intelligent HART Temperature Transmitter

**User Manual** 





# Warning

1. It is forbidden for users to disassemble the temperature module by themselves.

2. Please check if the supply voltage of temperature transmitter meets the power supply voltage requirements in the manual.



# **Company Introduction**

Microcyber Corporation, established as a high-tech enterprise by the Shenyang Institute of Automation Chinese Academy of Sciences, mainly engages in advanced industrial control systems, equipments, instruments and chips for industrial process automation control solutions in the research, development, production and application. Microcyber undertakes a number of national scientific and technical key task and "863" project, and has Liaoning Province networked control systems engineering research center.

Microcyber successfully developed the FF H1 fieldbus protocol stack which is number one to be approved internationally in China, and the Industrial Ethernet Protocol(HSE) which is number one to be approved in China, and the domestic first fieldbus instrument which has a function of national-level intrinsically safe explosion--proof and safety barrier. Also Microcyber participated in the drafting of the domestic first Ethernet-based industrial automation protocol standards (Ethernet for Plant Automation, EPA). As a result, serial products are composed of configuration, control software, embedded software, control system, instrument chip to the OEM board, and make Microcyber be an industrial automation products provider in full range, and also further Microcyber's leading position in the field of fieldbus technology.

Microcyber is the member of FCG (FieldComm Group) and PNO (Profibus National Organization).

Microcyber passed the Authentication of ISO 9001 Quality System,

and has an outstanding innovative R&D team, plentiful practical experiences of design of the Automatic engineering, a leading product series, a huge market network, a strict quality management system and an excellent enterprise culture. All these further a solid foundation of entrepreneurship and sustainable development for Microcyber.

Carrying the ideals of employees, creating customer value and promoting enterprise development.

Microcyber is making progress with China.



# Catalogue

1	Brief	f Introduction	1
2	Insta	llation	2
	2.1	Dimension	2
	2.2	Installation	
	2.3	Wiring	3
3	HAR	T Temperature Transmitter Configuration	5
	3.1	Topology Connection	5
	3.2	Functional configuration	6
4	Main	itenance	17
5	Tech	nical Specification	
	5.1	Basic Parameter	
	5.2	RTD Parameter	19
	5.3	Thermocouple	19
	5.4	Physical Parameter	20
		-	

# **1 BRIEF INTRODUCTION**

NCS-TT106H-V2.0 fieldbus temperature transmitter, using the fieldbus technology, is a new generation of smart fieldbus temperature transmitter and it is an indispensable field device for process control. NCS-TT106H-V2.0 integrates abundant function blocks and realizes not only general measurement function but also complicated control strategy.

NCS-TT106H-V2.0 uses digital technology, so it can connect with many types of thermocouple and thermo resistive sensors. It has wide range and simple interface between field and control room, which reduces the expense of installation, operation and maintenance.

NCS-TT106H-V2.0 fieldbus temperature transmitter supports HART, FF, and PA protocols. It can be widely used in the petroleum, chemicals, electricity, and metallurgical industries, etc.



# **2** INSTALLATION

## 2.1 Dimension



Figure 2.1 Dimension of Temperature Transmitter (Unit: mm)



## 2.2 Installation

Via positioning hole, use two screws to install the temperature module to temperature housing or rail.





2.3 Wiring



Figure 2.3 Wiring

Fieldbus temperature transmitter power and bus signal share a pair of cable, and it is called bus cable. It is suggested the user use fieldbus special cable recommended by IEC61158-2.

The signal cable and bus cable cannot share wires or wire slot with other device power wire, and they shall be away from device with high power.

The shielded wires of bus ends shall be connected to the ground.

# 3 HART TEMPERATURE TRANSMITTER CONFIGURATION

## 3.1 Topology Connection

The connection mode of HART smart transmitter can be divided into 4~20mA compatible mode and networking mode.

4~20mA compatibility mode (as shown in Figure 3.1)



Figure 3.1 4~20mA compatible mode

Features:

1) Access to the upper level control system through the AI module and

HART communication device;

2) Mixed use of analog and digital communication methods;

3) The device address is 0.





### Networking mode (as shown in Figure 3.2)

Figure 3.2 HART Networking mode

Features:

1) Access to the upper level control system through the HART communication device;

2) Using only the digital function of the HART system, the current on the line is fixed at 4 mA;

3) Supports up to 64 device networking in short address format.

## 3.2 Functional configuration

The intelligent temperature transmitter supports Microcyber Corporation's HARTMPT configuration software, HART FCG's SDC625 and other general HART configuration software for configuration debugging. The following is an example of Microcyber's HARTMPT configuration software to introduce the configuration method of the intelligent temperature transmitter. It mainly includes the following functions:

1) Basic information configuration: configure the basic information

of the online device, including the label, address, date, assembly number and other information;

2) Configuration information configuration: configure the configuration information of the online device, including the main variable range, damping and other information;

3) Sensor information configuration: configure sensor information of the online device, including type, line system and other information;

4) Current calibration: It can calibrate the 4~20mA current of the online device, and can also set the fixed current output;

5) Variable monitoring: It can periodically refresh all dynamic variables of the selected online device and display the trend curve of the current device host variable.

### • Configuration environment

1) PC with serial port, operating system is Windows 2000\Windows XP;

2) HART Modem and serial cable;

3) Matching resistance is  $250\Omega \sim 550\Omega$ .

### Basic information configuration

The basic information tab allows you to read or modify the basic information of the smart transmitter, including device address, message, description, label, date, assembly number, alarm, write protection, manufacturer ID, manufacturer, device type, device ID., long address and version information, as shown in Figure 3.3.

USB Serial Port (COI	Info Config Sens	or 线性修正 CurrentAdj Device Scan			
🗹 🏇 TAG00000@Po	Transmitter Infom	ation			
		Apply			
	Descrption	SMART INSTRUMENT			
	Tag	TAG00000	Alarm Type	High	
	Date	2007 / 11 / 9	Write Protect	Disable	
	Assembly	000000	Vendor ID	601E	
	Identification		Revision		
	Manufacturer	Microcyber Inc.	Universal	7	
	Туре	NCS-TT 106H	Device	1	
	Device ID	40 11 F9	Hardware	4	
	Unique ID	E4 0A 40 11 F9	Software	2.6	

Figure 3.3 Basic Information

After the information is modified, you can download it to the device by pressing the "Apply" button.

1) The selection range of the address is 0 to 63;

2) The message can be entered up to 32 characters;

3) Description can input up to 16 specified characters;

4) The maximum length of the label is 8 specified characters;

5) The date range is from 1900 to 2155;

6) The maximum length of the assembly number is 6 specified characters.

#### • Configuration information configuration

The smart transmitter configuration information can be read or modified via the configuration information tab.



Including display device output variables (main variable, cold junction temperature value, current value, percentage), setting of main variable information (damping value, unit, range upper limit, range lower limit), calibration of range and alarm current Settings, etc., as shown in Figure 3.4.

💥 Hart Mass Production Tool		$\times$
File(F) View(V) Device(D) W	Nindow(W) Setting(S) Help(H)	
🎶 🐹 🖉 🔇		
USB Serial Port (CO)	Info Config Sensor 线性修正 CurrentAdj Device Scan	
✓ 🏇 TAG00000@Po	Output PV Setting Alarm Setting	
	PV 9999.999 °C Type SENSOR_1 V Type High V	
	Cold Temp. 33.875 °C Dump 0.0 Sec Value 21.750	
	Current 21.750 mA Unit °C 🗸	
	Percent 1176.470 % Apply Setting:	
	Up Limit 850.000 ℃	
	Low Limit 0.000 °C	
	SET by current value:	
	Up Limit Low Limit	
	PV Zero Point	
	TT EXPLORE	
< >		
No Command Specific Errors	NUM	

Figure 3.4 Configuration information

- Damping: Range 0 to 32 seconds.
- Unit: The change of PV unit directly affects the variables associated with the unit, such as the upper and lower limits of. the range, the upper and lower limits of the sensor, and so on. When modifying the unit, you cannot modify the upper and lower limits of the main variable range at the same time, and should be modified separately.

- > The unit can be set to: C', F', R', K, mV, Ohm.
- > Upper range: PV value corresponding to 20mA output current.
- > Lower range: PV value corresponding to 4mA output current.
- > Alarm type: high alarm and low alarm.
- Alarm value: When the alarm type is high alarm, it can be 21.75mA to 23.00mA

The alarm current is set within the range; when the alarm type is low alarm, the alarm current can be set within the range of 3.50mA to 3.75mA.

After the information is modified, you can download it to the device by pressing the "Apply" button.

- Set the "Range Upper Limit" button with the current value: set the current PV value of the device to the upper limit of the main variable range, and the lower limit of the range.
- Set the "Lower Limit" button with the current value: Set the current PV value of the device to the lower limit of the main variable range, which may change the upper limit at the same time.
- Set the "Main Variable Zero" button with the current value: Use the current PV value of the device as the main variable zero.

## Sensor configuration

The sensor information tab allows you to view the currently configured sensor information (upper, lower, and minimum spans) and to configure each sensor type, line, and other information. As shown in Figure 3.5.



USB Serial Port (CO)	Info Config	Sensor 线性修正 CurrentAdj	Device Se	tan		
✓ <sup>™</sup> TAG00000@Po	Sensor Setting			Restore Setting	High-Low Level C	alibration
	Туре	PT100 ~				
	Wire Check	Open & Short 🔍			Enable Lev	Close Level
	Conn	Four Wres $\sim$		Restore to the default factory		
	Cold Temp.	INTER ~				
	Channel	CHANNEL OPEN	Apply	Restore to factory	Calibration Poin	Zero Liquid Level $\sim$
	Sensor Value	65851.000			Caliburation Univ	
	Cold Temp	34.000	ic i	Save as default	Calbration valu	e 0.000000 me.e
						Apply
	Sensor Calibrate	1.000000	Courset			Sensor
	KO AUJUSI		correct			Up Limit 850.000 °C
			2-Wire Ze	ro Calbrate		Law Linit 200,000
		т	C Calibrate(E	xternal mV Signal)		contrast contrast c
		TC Calibr	ate(Full range	e internal self-calibration)		Min Span 10.500 °C
	Four-Wire Calibr	rate				
		RTD Calibrate	0 ohr	Value 400.000		
		RTD Calibrate(0_500R)	400 c	hm Value 3200.000 0	Download	
			4000	50 000 m	/	
		RTD Calibrate(0_4000R)	3800	ohm Value	·	

Figure 3.5 Sensor configuration

## Sensor type: supported sensor models are as below:

Sensor type	Description		
0_500R	Resistance, $0 \approx 500\Omega$		
0_4000R	Resistance, $0 \approx 4000\Omega$		
CU50	Cu50		
CU100	Cu100		
PT100	PT100		
PT1000	PT1000		
100MV	mV voltage signal, range: -100 ~ 100 mV		
B_TC	B thermocouple		
E_TC	E thermocouple		

J_TC	J thermocouple
K_TC	K thermocouple
N_TC	N thermocouple
R_TC	R thermocouple
S_TC	S thermocouple
T_TC	T thermocouple

Wiring system: It can be set to 2-wire system, 3-wire system and 4-wire system, only effective for RTD.

- Cold-end temperature compensation: it can be set to prohibit, internal measurement and external measurement. When the cold-end temperature compensation is prohibited, the transmitter will not carry out the cold-end temperature compensation; when the cold-end temperature compensation is enabled to measure internally, the value of the cold-end temperature compensation is measured by the internal temperature measuring chip; when the cold-end temperature compensation is enabled to measure externally, the external two-wire system Pt100 is used, and then the value of the coldend temperature compensation is measured by the external Pt100.
- Channel status: Display sensor channel status (open circuit, short circuit & etc.).
- Sensor channel value: Display the original value of sensor channel.
- Cold end temperature: Display the current cold end temperature.
- R0 Correction Factor: Correction of the error of the sensor

itself (range 0.9-1.1).

- Two-wire zero calibration: When the temperature transmitter is connected to RTD in 2-wire mode, to avoid the error caused by the resistance on the cable, the sensor end can be short connected, and then the zero calibration button can be executed to eliminate the error caused by the resistance on the cable.
- TC Calibration: Calibration of various thermocouple ranges of transmitters is carried out in the factory (only applicable to manufacturer-level users).
- RTD calibration: All kinds of resistance ranges of transmitter are calibrated out of the factory (only for manufacturer-level users).
- "500 ohm gear", "4000 ohm gear" and "mv gear" are the calibration points of the transmitter. The calibration points can be modified. Click "download" to write the new calibration points into the module.
- Restore factory default value: Click this button, all data will be restored to the default factory status.
- Save as factory value: Click this button to save the current configuration as factory value. When you click the "Restore factory settings" button again, the saved configuration will be restored.
- Restore factory settings: Click this button to restore data to factory status. If the user has saved the factory value, the configuration saved by the user will be restored; otherwise, the default factory status will be restored.
- > High and low liquid level calibration: Turn on the function of

the transmitter to measure liquid level through "Enable liquid level" and "Prohibit liquid level". After the liquid level is enabled, the liquid level needs to be calibrated by calibrating the zero and full points of the liquid level.

### Current Calibration

### The current calibration steps are as follow:

1) To connect the circuit, more than five and a half bits ammeter should be connected in series in the output circuit of the equipment.

2) Set the polling address of the device to be 0. Refer to the basic information configuration. If the polling address is 0, you can skip this step.

3) Enter the current calibration tab;

4) Select the current value as 4mA. After the ammeter is stable, input the ammeter reading in the text box of "Adjustment Value" and click the "Application" button.

5) Select the "current value" of 20 mA. After the ammeter is stabilized, enter the ammeter reading in the "adjustment value" text box and click the "application" button.

6) Select "current value" as blank, so that the output current of the equipment is calculated according to PV value.

### Configuration current fixed output:

Users can configure a fixed current output in the current calibration tab, click the given fixed current value or "Manual Send" and fill in the fixed current value to be output, click "Enter/Exit Fixed Current Mode" to enter or exit the fixed current output mode. The title of the button alternately displays "Enter Fixed Current Mode" and "Exit Fixed Current Mode" to prompt the user to operate.



HART intelligent transmitter continuously compares main variable value with the upper and lower limit value. When main variable value exceeds the upper and lower limit, the module outputs fixed current, indicating that the main variable exceeds the range. When the main variable is higher than the upper limit, the output is fixed at 20.8 mA. When it's lower than the lower limit, the output is fixed at 3.8 mA.

	Window(W) Setting(S) Heip(H)	
11 🔀 🖉 🖉		
USB Serial Port (C)	Info Config Sensor Liner Revise CurrentAdj Device Scan	
🗹 🎲 TAG00000@F	Fixed Output	
	(e) 3.8 mA () 16.0 mA	
	0 4.0 mA 0 20.0 mA	
	○8.0 mA ○21.0 mA	
	O 12.0 mA O Manually send mA	
	Could a mark Made	
	Fixed Current Mode	
	Calibrate	
	Use standard ammeter	
	Use standard 250 ohm resistor	
	O Use other standard resistance, value	
	Value  Value Apply	
	Value Apply Adjust Apply	
	Value Apply Adjust	
	Value V Apply Adjust Apply	
	Value V Apply Adjust Apply	
	Value Apply Adjust Apply	
	Value V Apply Adjust Apply	

Figure 3.6 Current calibration

**Note:** Calibration current and fixed current output function can only be performed when device's polling address is 0. Other polling addresses are in complete digital communication mode, which will prompt the error message "command execution failure".

#### • Variable monitoring

Through the variable monitoring tab, all dynamic variables of the



selected equipment can be refreshed regularly and the trend curve of the main variables of the current equipment can be displayed. Currently, the refreshed variables are PV value, current value, percentage and cold end temperature.



Figure 3.7 Variable monitoring

# **MAINTENANCE**

Phenomenon	Solution
	Temperature Module Connection
	Check the bus cable connection
NI-	Check bus power polarity
NO	Check bus cable shield, whether it is single point earthing
communication	or not
	Temperature Module Failure
	Replace the temperature module with others for testing.
	Temperature Module Connection Failure
	Check sensor short circuit, open circuit, and earthing.
	Check sensor
	Noise Disturb
	Adjust damping
	Check the house earthing
	Check if the terminal is moist
Reading Error	Check the cable is away from the strong electromagnetic
	interference
	Software Configuration
	Check sensor type configuration
	Check function block parameter configuration
	Software Configuration
	Check sensor type configuration
	Check function block parameter configuration



# **5** TECHNICAL SPECIFICATION

### 5.1 Basic Parameter

	Pt100、Pt1000、CU50、CU100、O $\sim$ 500 $\Omega$ 、O $\sim$ 4000 $\Omega$			
Input Signal	B, E, J, N, K, R, S, T eight kinds of Thermocouple			
	-100mV $\sim$ 100mV voltage signal			
Channel	Single			
RTD Wiring	2-wire, 3-wire, 4-wire			
Bus Power	HART: 11 $\sim$ 35 VDC			
Bus Signal	HART,current mode			
Electric isolation	1000VAC			
Working	40% - 05%			
Temperature	-40°L∼85°L			
Humidity Range	5%~95%RH			
Start Time	≤5s			
Refresh Time	0.5s			
EMC	GB/T 18268.1-2010, EN61326.1-2013			
Protection	Terminal IP00, housing IP40			
Voltage effect	±0.005%/V			
Alarm signal	Alarm output can be set as 3.523 mA			
Aldrift Signal	Upper/lower limit current 20.8mA / 3.8mA			
Current	0.02%			
accuracy	0.05%			
Intrinsically safe				
explosion-proof	Ex ia IIC T4 Ga			
(optional)				

### 5.2 RTD Parameter

#### • RTD Parameter at Normal Temperature

Signal	Suggested range	Accurrent (25%C)	Temperature drift
type			(per ℃)
Resistance	0~500Ω	±0.04Ω	±0.001Ω
Signal	0~4000Ω	±0.35Ω	±0.015Ω
PT100	-200 ~ 850°C	±0.15°C	±0.003°C
PT1000	-200 ~ 850°C	±0.15°C	±0.005°C
CU50	-50 ~ 150°C	±0.15°C	±0.005°C
CU100	-50~ 150°C	±0.10°C	±0.003°C

#### RTD Other Parameter

Wiring	2、3、4
Common Mode Rejection	≥70dB (50Hz and 60Hz)
Series Mode Rejection	≥70dB (50Hz and 60Hz)

### 5.3 Thermocouple

#### • Thermocouple Parameter at Normal Temperature

Signal type	Suggested range	Accuracy	Temperature drift
		(25℃)	(per ℃)
mV	-100mV ~ +100mV	±0.025mV	±0.001 mV
В	500 °C~ 1810°C	±0.77°C	±0.050°C
E	-200 °C~ 1000°C	±0.20°C	±0.025°C
J	-190 °C~ 1200°C	±0.35°C	±0.01°C
К	-200°C ~ 1372°C	±0.40°C	±0.025°C
Ν	-190°C ~ 1300°C	±0.50°C	±0.015°C
R	0°C ~ 1768°C	±0.75°C	±0.023°C
S	0 °C~ 1768°C	±0.70°C	±0.023°C



T -200°C ~ 400°C	±0.35°C	±0.015°C
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#### • Thermocouple Other Parameter

Compensation	±0.5°C	
Accuracy		
Sensor Type	B, E, J, N, K, R, S, T; -100mV $\sim$ +100mV	
Common Mode	NZOND (FOUL and COUL)	
Rejection		
Series Mode	$\geq$ 70dB (50Hz and 60Hz)	
Rejection		
Temperature Effect	<50ppm/°C	

## 5.4 Physical Parameter

Dimension	¢45*23mm
Housing Material	Nylon

Microcyber Corporation Http://www.microcyber.cn/en Add: 17-8 Wensu Street, Hunnan New District, Shenyang, China 110179 Tel: 0086-24-31217278/31217280 Fax: 0086-24-31217293 Email: sales@microcyber.cn